# Creating Flowcharts in $\mathrm{ET}_{\mathrm{E}} \mathrm{X}$ <br> Using the pic Language * 

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## 1 Introduction

This tutorial document explains how to create flowcharts in $\mathrm{EA}_{\mathrm{E}} \mathrm{X}$ using the pic language developed by Brian W. Kernighan for typesetting graphics [1]. The pic language provides an easy and flexible way to create procedural box-andarrow diagrams, state flow charts, circuit layouts and other drawings involving repetitive uses of simple geometric forms and splines. The illustrations produced with pic can be easily included in troff and $\mathrm{IAT}_{\mathrm{E} X}$ documents. An important advantage of using $p i c$ is that the figures are in vector form rather than bitmaps, thus can be scaled and stored in compact files without altering the quality of the graphs.

The purpose of this to quickly get you on the right track to producing flowcharts that can be included in $\mathrm{AT}_{\mathrm{E}} \mathrm{X}$ documents using. This document is not intended to serve as a pic tutorial, but it provides references to the documentation where you may find elementary examples, sample pictures, and other details that your are encouraged to check if you are unfamiliar with the pic language.

## 2 Steps to Create Flowcharts and Other Graphs with pic

The steps can be summarized in:

1. Write a description of your figure or flowchart using the pic language.
2. Convert your pic diagram into either of:
(a) Code containing PSTricks commands by executing the dpic interpreter as follows:
[^0]```
dpic -p fig.pic > fig.tex
```

(b) Code containing tpic \special commands by executing the GNU pic interpreter as follows:
gpic -t fig.pic > fig.tex
or

```
pic -t fig.pic > fig.tex
```

if a newer version of groff is installed in your system.
IMPORTANT: When processing the $*$.pic files provided with this document, the variable pstricks in the $*$.pic files must be set to 0 if gpic is used or to 1 when dpic is used.
3. Depending on whether gpic or dpic were used in the previous step, include fig.tex in your document respectively as follows:

```
(a) \begin{document}
```

```
\begin{figure}[htbp]
```

[htbp]
{
{
\input fig.tex
\input fig.tex
\centerline{\box\graph}
\centerline{\box\graph}
}
}
Figure 1: Figure title.

\end{figure}

..
..
nd{document}\end{document}(b)\begin\{document\}}\usepackage{pstricks}...undefinedundefinedundefinedundefinedundefinedundefinedundefinedundefined

[htbp]
{

\input fig.tex
}
Figure 2: Figure title.

...
\end{document}

```

The next sections briefly explain where to find the information and tools to accomplish steps 1 and 2 . Step 3 should be pretty straight forward as may be seen from the source code for the inclusion of this document's figures (see file flowchart.tex).

\section*{3 Drawing Flowcharts with pic}

Making figures with pic is well described in the following documents that are available on Internet:
[1] B. W. Kernighan. PIC - A Graphics Language for Typesetting (Revised User Manual) Bell Labs Computing Science Technical Report \#116, December 1991. Available at:
http://www.cs.bell-labs.com/10thEdMan/pic.pdf.
\(\rightarrow\) This is the classic pic manual and a "must read".
[2] E. S. Raymond. Making pictures with GNU PIC, 1995. In GNUgroff source distribution.
\(\rightarrow\) This is a more complete pic manual. See reference [5] at the end of this document for information on where to get the groff package.
[3] J. D. Aplevich. M4 Macros for Electric Circuit Diagrams in \(L^{A} T_{E} X\) Documents, version 6.4, 2008. Available at:
http://texcatalogue.sarovar.org/entries/circuit-macros.html or the Comprehensive \(\mathrm{T}_{\mathrm{E}} \mathrm{XArchive}\) Network (CTAN, http://www.ctan.org) mirrors.
\(\rightarrow\) This document is about the \(L^{A} T_{E} X p a c k a g e ~ c i r c u i t-m a c r o s, ~ w h i c h ~ i s ~\) based on M4 macros and pic. This package contains an excellent collection of PIC macros for many circuit components and other schematic diagrams blocks. It is a "must read" because it provides a good set of references and a concise explanation about the methodology to create pic drawings using the gpic or dpic interpreters. The circuit-macros documentation played a key role in the preparation of this tutorial and the flowchart macros and examples.
[4] J. D. Aplevich. Dpic package, version 29 Oct. 2008. Available at: http://www.ece.uwaterloo.ca/ aplevich/dpic/.
\(\rightarrow\) Read the README and the MAN file (manual) for more information on the dpic interpreter.
[5] Groff for Windows, version 1.19.2. Available at:
http://gnuwin32.sourceforge.net/packages/groff.htm.
The package homepage is:
http://www.gnu.org/software/groff/groff.html.
\(\rightarrow\) Read the MAN file (manual) of gpic (also known as pic) for more information on gpic, the GNU pic interpreter.

There is no point in repeating the good explanations found in these references. If you are unfamiliar with pic and cannot figure out the meaning of the drawing commands in the *.pic files provided as examples with this document, you should read the references in the order in which they have been listed to get a good basis of pic's capabilities and functionality.

Creating flowcharts with pic is not much different to the process of making a figure with pic. To facilitate the task of making flowcharts, a set of macros for the standard flowchart symbols was created (see Appendix A or the *.pic files for details on the macro definitions). In order to make your own flowcharts you must copy the macros from any of the *.pic files to a new file and write your code right after the macros. Do not forget to end your code with the . PE pic command. The structure of your pic file should look like:
```

.PS \#20/25.4 \# Scale drawing to 20/25.4 in =
\# =x 20/25.4[in]/25.4[mm/in] = 20 mm

# FLOWCHART - Basic flow chart blocks.

<<< HERE ARE THE MACRO DEFINITONS>>>
\#--- END OF MACROS ---
\#--- YOUR FLOWHART CODE STARTS HERE ---
<<< PLACE YOUR FLOWCHART CODE HERE>>>

```
.PE

The macros receive as arguments the scaling factors for the horizontal ( \(s x\) ) and vertical (sy) dimension of the symbol. Only the connector symbol receives one scaling factor \((s)\) because it is a circle. The scaling factors multiply the basic unit length defined for the macros as parameter csize (cell size). For example, a symbol which is \(12 \times 8\) units or cells and that has been declared with \(s x\) set to 2 , sy set to 4 , will be \(24 \times 32\) units big. By default the cell size value is set to 2 mm , therefore, the scaled symbol will actually measure \(48 \times 64 \mathrm{~mm}\). The available macros are:
- process(sx,sy): makes a "process" block (rectangle).
- data(sx,sy): makes a "data input or output" block (parallelogram).
- connector(s): makes a connector symbol (circle).
- decision(sx,sy): makes a decision block (rhombus).
- preparation(sx,sy): makes a routine initialization or program preparation block (hexagon-like block).
- sf terminator(sx,sy): makes a terminating block ("flat slim sausage" block).
- keying(sx,sy): makes a block to represent a process or operation that involves typing or is driven by some manual input device ("flat fat sausage" block).
- keyboard(sx,sy): makes a block to represent a keyboard, switches or pushbuttons (quadrilateral block).
- document(sx,sy): makes a document symbol (rectangle with wavy line at the bottom).
- display(sx,sy): makes a display symbol to represent a computer screen or monitor, video devices, console printers, or other visual indicators.

The symbols produced by these macros are shown in the figure 1 , which was created with the following lines of code (see file flow0.pic):
```

down;
CO: connector(1);
arrow;
H0: preparation(1,1); "\sf Preparation" at HO.c;
move to HO.B.s;
arrow;
DO: data(1,1); "\sf Data" at DO.c;
move to DO.B.s;
arrow;
PO: process(1,1); "\sf Process" at PO.c;
move to PO.B.s;
arrow;
RO: decision(1,1); "\sf Decision" at RO.c;
move to RO.B.s;
arrow;
T0: terminator(1,1); "\sf Terminator" at T0.c;
move to RO.B.w;
left;
arrow;
KO: keying(1,1); "\sf Keying" at KO.c;
move to KO.B.w;
arrow invis;
K1: keyboard(1,1); "\sf Keyboard" at K1.c;
move to K1.B.e;
right;
arrow;
move to KO.B.n;
line -> dashed up C0.w.y-K0.n.y then right C0.w.x-K0.n.x;
move to PO.B.e;

```
```

right;

```
arrow;
WO: document (1,1); "\sf Document" at WO.c;
move to DO.B.e;
right;
arrow;
SO: display (1,1); "\sf Display" at SO.c;

It is to be noted that the sizing of the symbols was made according to the IBM flowcharting template [6], in which most symbols are \(12 \times 8\) units long and should also match those of the ISO standard [7]. Practically any flowchart can be prepared with these symbols. As a matter of fact, the basic blocks: process, data, connector, together with the processing and sequencing symbols: decision, preparation, terminator, should be sufficient for most flowcharting needs. The input/output and processing hardware related symbols can be replaced for data blocks without losx of clarity, as far as the data flow or algorithmic description are concerned.

Additional examples on the use of the macros are presented in the next subsections. For further information and references about flowcharts please check also [8] and references therein.

\subsection*{3.1 Basic Program Flow Structures}

Figure 2 shows the basic program flow structures: a simple sequential execution of three process, a conditional branching (If-Then-Else) and a program loop (While-Do loop). These simple flowcharts were generated by the following code (see file flowbs.pic):
```

\#Sequence
down;
S1: [move down 30;
arrow;PA: process(1,1); "\sf Process A" at PA.c;
move to PA.B.s;
arrow;PB: process(1,1); "\sf Process B" at PB.c;
move to PB.B.s;
arrow;PC: process(1,1); "\sf Process C" at PC.c;
move to PC.B.s;
arrow;box invis "{\Large {\sf Sequence}}";
]
move to S1.ne+(60,0);
\#If-Then-Else
I1: [arrow;
R1: decision(1,1); "\sf Decision" at R1.c;
move to R1.s;
arrow;

```


Figure 1: Basic flowchart symbols.
```

    P1: process(1,1); "\sf Process 1" at P1.c;
    move to P1.B.s;
    L1: line;
    move to R1.e; line -> right 20 then down R1.e.y-P1.n.y;
    P2: process(1,1); "\sf Process 2" at P2.c;
    move to P2.B.s;
    line -> down P2.s.y-L1.end.y then left P2.s.x-L1.end.x;
    down;arrow;box invis "{\Large {\sf If-Then-Else}}";
    ]
    move to I1.s-(0,5);
\#While-Do
W1: [L1: line;
arrow;
R1: decision(1,1); "\sf Decision" at R1.c;
move to R1.s;
arrow;
box invis "{\Large {\sf While-Do}}";
move to R1.e;
right;arrow;
P1: process(1,1); "\sf Process X" at P1.c;
move to P1.n;
line -> up L1.end.y-P1.n.y then left P1.n.x-L1.end.x;
]

```

\subsection*{3.2 Derived Program Flow Structures}

There exist two common program flow structures that can be derived from the previous ones. These are the Case-Of, which corresponds to a series of If-ThenElse statements, and the Do-Until loop, which is derived from the While-Do loop. The Do-Until loop is equivalent to always executing the code within the While-Do loop at least once before exiting the loop if the condition is not met. Other names for the Do-Until loop are Repeat-Until or the similar Do-While. These derived program flow structures are represented by the flowcharts shown in fig. 3, which was created with the following code (see file fileds.pic):
\#Case-Of
down;
CS1: [arrow;
R1: decision(1,1); "\sf Decision 1" at R1.c;
move to R1.s;
arrow;
R2: decision(1,1); "\sf Decision 2" at R2.c;
move to R2.s;
arrow;
R3: decision(1,1); "\sf Decision 3" at R3.c;


Figure 2: Basic program flow structures.
```

    move to R3.s;
    arrow;
    PD: process(1,1); "\sf Default" "\sf Process" at PD.c;
    move to PD.s;
    L1: line;
    move to R1.e;
    right;arrow;
    P1: process(1,1); "\sf Process 1" at P1.c;
    move to P1.e;
    P1A: arrow;
    move to R2.e;
    right;arrow;
    P2: process(1,1); "\sf Process 2" at P2.c;
    move to P2.e;
    arrow;
    move to R3.e;
    right;arrow;
    P3: process(1,1); "\sf Process 3" at P3.c;
    move to P3.e;
    arrow;
    move to P1A.end;
    line -> down P1A.end.y-L1.end.y then left P1A.end.x-L1.end.x;
    down;arrow;box invis "{\Large {\sf Case-Of}}";
    ]
    move to CS1.ne+(40,-35);
\#Do-Until
DU1: [L1: line;
arrow;
P1: process(1,1); "\sf Process" at P1.c;
move to P1.s;
arrow;
R1: decision(1,1); "\sf Decision" at R1.c;
move to R1.s;
arrow;
box invis "{\Large {\sf Do-Until}}";
move to R1.e;
line -> right 20 then up L1.end.y-R1.e.y then left R1.e.x+20-L1.end.x;
]

```

\subsection*{3.3 A real example}

To illustrate the application of the flowchart macros on a real example, consider the pseudocode of a color-based image segmentation process presented as algorithm 1. For every pixel \(p\) in an image, the algorithm computes a color feature \(f(p)\) and checks if the feature is within some threshold \(\lambda\) with respect to all the


Figure 3: Derived program flow structures.
different classes' reference feature vector \(f_{c}\). The two outer for-from-to-do loops correspond to the pixel position, while the inner loop corresponds to the testing with respect to each class \(c\). This algorithm can be describe in terms of the flowchart shown in fig. 4. In this flowchart example, the two outer for-from-to-do loops have been represented by a single for-from-to-do loop over the pixel position \(p\).
```

Algorithm 1: ProcessImage (Low-level Pseudocode)
input : \&img (input image), \&ProcessParam (process parameters)
output: \&img (segmented image)
\&imgaux $\leftarrow$ \&img;
—— ComputeSegmentation ——;
for row $=0$ to \&img.height do
for $\mathrm{col}=0$ to \&img. width do
for class $=1$ to \&ProcessParam.Nclasses do
if \|ConvertToYCrCb (\&imgaux(row,col))...
$-\&$ ProcessParam.FeatureVector(class) $\|<$ Threshold then
\&img $\leftarrow$ class;
end
end
end
end

```


Figure 4: Flowchart for a color-based image segmentation process.

The code that generates de flowchart in fig. 4 is (see file flowcs.pic):
```

alen = 25.4/4*0.8; \# arrow length
crad = 1/csize/2; \# connector radius in csize*2 units

# initialize the for loop on p (p is the pixel position)

down;
HO: preparation(1.5,0.5);
"\parbox{6em}{ \sf \&imgaux$\leftarrow$\&img;<br>
$p\leftarrow (0,0)$}" at HO.c;
move to HO.B.s;
arrow alen;
CO: connector(crad);
arrow alen;

# check if the for loop on p is done

RO: decision(1,1);
"\parbox{6em}{ \sf $p\in\mathcal{D}_I$}" at RO.c;
move to RO.B.w; "\sf no" above rjust;
move to RO.B.s; "\sf yes" below ljust;
move to RO.B.s;
arrow alen;
P0a: process(1,0.8);
"\parbox{6em}{ \sf \small Compute<br>
feature vector<br> $f(p)$}" at P0a.c;
move to POa.B.s;
arrow alen;

# initialize the for loop on c (c is the class label)

H1: preparation(1.5,0.5);
"\parbox{6em}{ \sf $c=0$}" at H1.c;
move to H1.B.s;
arrow alen;
C1: connector(crad);
arrow alen;

# check if the for loop on c is done

R1: decision(1,1);
"\parbox{6em}{ \sf $c<N_{classes}$}" at R1.c;
move to R1.B.w; "\sf no" above rjust;
move to R1.B.s; "\sf yes" below ljust;
move to R1.B.s;
arrow alen;

```
```


# check if the feature at pixel p, f(p) can be classified

# as the class c, due to the proximity with respect to

# the class feature vector f_c

R1a: decision(1,1);
"\parbox{7em}{ \sf
\footnotesize $\|f(p)-f_c\|<\lambda$}" at R1a.c;
move to R1a.B.w; "\sf no" above rjust;
move to R1a.B.s; "\sf yes" below ljust;
move to R1a.B.s;
arrow alen;
P1a: process(1,0.5);
"\parbox{6em}{ \sf \&img($p$)=$c$}" at P1a.c;
move to P1a.B.s;
down; arrow alen;
C1e: connector(0.1);
move to R1a.B.w;
left; line; line alen;
line -> down R1a.c.y-P1a.n.y;
P1b: process(1,0.5);
"\parbox{6em}{ \sf \&img($p$)=$0$}" at P1b.c;
move to P1b.B.s;
line -> down P1b.s.y-C1e.c.y then right to C1e.w;
move to C1e.s;
down; arrow alen;
P1: process(1,0.8);
"\parbox{6em}{ \sf Increment class<br>
$c\leftarrow c+1$}" at P1.c;
move to P1.B.s;
L1a: line alen;

# close for loop on c

move to L1a.end;
right; line; line;
up; line C1.c.y-Here.y;
left; line -> to C1.e;

# end for loop on c

move to R1.B.w;
left; line; line; line;
line down R1.B.w.y-P1.B.s.y+2*alen;
line right P1.B.c.x-Here.x;

```
```

L1b: arrow down alen;
move to L1b.end;
down;
PO: process(1,0.8);
"\parbox{6em}{ \sf Update position<br>
$p\leftarrow p+\Delta p$}" at PO.c;

# close for loop on p

move to PO.B.s;
line down alen;
right; line; line; line;
line up CO.c.y-Here.y;
line -> left to CO.e;

# end for loop on p

move to RO.B.w;
left; line; line; line; line;
line down RO.B.w.y-PO.B.s.y+2*alen;
line right PO.B.c.x-Here.x;
LOb: arrow down alen;
T0: terminator(1,0.5);
"\parbox{6em}{ \sf End}" at TO.c;

```

\section*{4 Compiling pic drawings to \(\mathrm{EAT}_{\mathrm{E}} \mathrm{X}\)}

Processing pic code can be done using dpic or the GNU pic interpreter (gpic). The output formats produced by dpic and gpic are completely different (see Ch. 12 of the circuit-macros documentation [3] or the dpic manual [4] for a complete description of the multiple formats). The differences can be summarized in:
- dpic produces PSTricks commands.
- gpic produces tpic ( \(\mathrm{T}_{\mathrm{E}}\) pic) \special commands that have to be later processed with a printer driver that understands tpic \special commands, such as dvips.

Depending on the approach chosen and the version of your dvi or Postscript viewer, the output produced with gpic may be correctly displayed only under the Postscript viewer (e.g. gv, Ghostview), but not under the dvi viewer (e.g. \(X d v i, Y a p)\). On the other hand, dpic requires the PSTricks \(\mathrm{IAT}_{\mathrm{E}} \mathrm{X}\) package to be installed and included in your \(\mathrm{AT}_{\mathrm{E}} \mathrm{X}\) file, while the output produced by gpic does not require the use of any additional package.

As stated in section 2 , converting from *.pic to \(*\). tex can be done using one of the following alternatives:
(a) Using dpic [4]:
```

dpic -p fig.pic > fig.tex

```
(b) Using gpic [5]:
gpic -t fig.pic > fig.tex
or with
pic -t fig.pic > fig.tex
if a newer version of groff is installed in your system.
IMPORTANT: When processing the \(*\).pic files provided with this document, the variable pstricks in the \(*\).pic files must be set to 0 if gpic is used or to 1 when dpic is used.

Once the *.tex files are produced with any of the two previous methods, the last step is to include them into your \(\mathrm{IAT}_{\mathrm{E}} \mathrm{X}\) document according to the corresponding approach, as explained in the third point of section 2 (see also the source code of the examples provided with this document).

\section*{References}
[1] B. W. Kernighan. PIC - A Graphics Language for Typesetting (Revised User Manual) Bell Labs Computing Science Technical Report \#116, December 1991. Available at: http://www.cs.bell-labs.com/10thEdMan/pic.pdf.
[2] E. S. Raymond. Making pictures with GNU PIC, 1995. In GNUgroff source distribution.
[3] J. D. Aplevich. M4 Macros for Electric Circuit Diagrams in \(L^{A} T_{E} X\) Documents, version 6.4, 2008. Available at: http://texcatalogue.sarovar.org/entries/circuit-macros.html or the CTAN http://www. ctan.org mirrors.
[4] J. D. Aplevich. Dpic package, version 29 Oct. 2008. Available at: http://www.ece.uwaterloo.ca/ aplevich/dpic/.
[5] Groff for Windows, version 1.19.2 Available at: http://gnuwin32.sourceforge.net/packages/groff.htm. The package homepage is: http://www.gnu.org/software/groff/groff.html.
[6] International Business Machines Corporation. IBM Flowcharting Techniques. IBM Technical Publications Dept. Document No. C20-8152-1, New York, 1069. Available at: http://www.fh-jena.de/kleine/history/software/... ...IBM-FlowchartingTechniques-GC20-8152-1.pdf.
[7] ISO 5807:1985 Standard: Information processing - Documentation symbols and conventions for data, program and system flowcharts, program network charts and system resources charts. Available at: http://www.iso.org/iso/iso_catalogue/catalogue_tc/... ...catalogue_detail.htm?csnumber=11955.
[8] Wikipedia. Flowchart. Visited on December, \(17^{\text {th }}, 2008\). http://en.wikipedia.org/wiki/Flowchart.

\section*{Appendix A pic Flowchart Macros}

The macros implemented to produce the flowcharts in this document were defined as pic language blocks. These blocks provide flowchart primitives by grouping into a single object or entity the lower level primitives of the pic language, such as lines, boxes and arcs. Not surprisingly, the pic language primitives grouped to form an object are called blocks in the terminology of the pic language. The following code shows the implementation of the macros developed to plot the flowchart symbols of the examples presented in this document. The code of these macros should be included at the beginning of your own flowcharts as explained in section 3 .
```

.PS \#20/25.4 \# Scale drawing to 20/25.4 in =
\# = 20/25.4[in]/25.4[mm/in] = 20 mm

# FLOWCHART - Basic flow chart blocks.

scale=25.4 \#Scale units from inches to mm
csize=2.0 \#Cell size in mm
pstricks=1
dx=0; dy=2;
\#sshade(): Starts shading of an arbitrary closed curve.
define sshade
{
if pstricks==0 then
{
sprintf("\special{sh %g}",0.1)
\#command "\special{sh 0.1}"
} else
{
\#sprintf("\newgray{xcolor}{%s}",0.9)
command "\newgray{xcolor}{0.9}"
command "\pscustom[fillstyle=solid, fillcolor=xcolor]{"
}
}
\#eshade(): Ends shading of an arbitrary close curve.
define eshade
{
if pstricks==1 then
{
command "}%"
}
}
define process
{[
w=\$1*12*csize; h=\$2*8*csize;
B: box wid w ht h invis;
sshade;

```
```

    line from B.ne to B.nw to B.sw to B.se to B.ne;
    eshade;
    #$3 at B.c;
    ]}

# data(): parallelogram -> "data input/output block"

define data
{[
w=\$1*12*csize; h=\$2*8*csize;
dx=(h/4)/2;
B: box wid w ht h invis;
sshade;
line from B.sw-(dx,0) to B.se-(dx,0) to B.ne+(dx,0)
to B.nw+(dx,0) to B.sw- (dx,0);
eshade;
\#\$3 at B.c;
]}
define connector
{[
r=\$1*2*csize;
sshade;
B: circle rad r;
eshade;
\#\$3 at B.c;
]}

# decision(): rhomboid -> "if block"

define decision
{[
w=\$1*12*csize; h=\$2*8*csize;
B: box wid w ht h invis;
sshade;
line from B.n to B.e to B.s to B.w to B.n;
eshade;
\#\$3 at B.c;
]}
define preparation
{[
w=\$1*12*csize; h=\$2*8*csize;
dx=(h/2)/2;
B: box wid w ht h invis;
sshade;
line from B.w to B.nw+(dx,0) to B.ne-(dx,0) to B.e
to B.se-(dx,0) to B.sw+(dx,0) to B.w;
eshade;
\#\$3 at B.c;
]}
define terminator

```
```

{[
w=\$1*12*csize; h=\$2*4*csize;
r=h/2;
B: box wid w ht h invis;
sshade;
line from B.sw+(r,0) to B.se-(r,0);
right; arc rad r from Here to B.ne-(r,0);
line from Here to B.nw+(r,0);
left; arc rad r from Here to B.sw+(r,0);
eshade;
\#\$3 at B.c;
]}
define keying
{[
w=\$1*14*csize; h=\$2*8*csize;
dx=(h/4)/2;
r=dx/2+(h/2) ^2/(2*dx);
B: box wid w ht h invis;
sshade;
line from B.sw+(dx,0) to B.se-(dx,0);
left; arc rad r from Here to B.ne-(dx,0);
line from Here to B.nw+(dx,0);
right; arc rad r from Here to B.sw+(dx,0);
eshade;
\#\$3 at B.c;
]}
define keyboard
{[
w=\$1*12*csize; h=\$2*5*csize;
dy=(w/6)/2;
B: box wid w ht h invis;
sshade;
line from B.nw-(0,dy) to B.sw to B.se
to B.ne+(0,dy) to B.nw-(0,dy);
eshade;
\#\$3 at B.c;
]}
define document
{[
w=\$1*12*csize; h=\$2*7*csize;
dy=(w/6)/2;
r=sqrt((w/2) ^2+dy^2);
B: box wid w ht h invis;
sshade;
line from B.se+(0,dy) to B.ne to B.nw to B.sw;
up; arc rad w/2 from B.sw to B.s;

```
```

    arc cw rad r from B.s to B.se+(0,dy);
    eshade;
    #$3 at B.c;
    ]}
define display
{[
w=\$1*12*csize; h=\$2*8*csize;
dx=1.5*(h/4)/2;
r=dx/2+(h/2)^2/(2*dx);
B: box wid w ht h invis;
sshade;
line from B.sw+(4*dx/1.5,0) to B.se-(dx,0);
left; arc rad r from Here to B.ne-(dx,0);
line from Here to B.nw+(4*dx/1.5,0);
arc rad r from Here to B.w;
right; arc rad r from Here to B.sw+(4*dx/1.5,0);
eshade;
\#\$3 at B.c;
]}
\#--- END OF MACROS ---

```
```


[^0]:    *Document revision 2. (First version, July $16^{t h}$, 2001).

